

**Class XI**  
**PHYSICS FULL SYLLABUS – 1**

**Time : 3 Hrs**

**M.M – 70 Marks**

**General Instructions :**

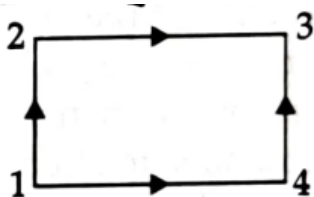
- (1) There are 33 questions in all. All questions are compulsory.
- (2) This question paper has five sections: Section A, Section B, Section C, Section D and Section E.
- (3) All the sections are compulsory.
- (4) Section A contains sixteen questions, twelve MCQ and four Assertion Reasoning based of 1 mark each, Section B contains five questions of two marks each, Section C contains seven questions of three marks each, Section D contains two case study based questions of four marks each and Section E contains three long answer questions of five marks each.
- (5) There is no overall choice. However, an internal choice has been provided in one question in Section B, one question in Section C, one question in each CBQ in Section D and all three questions in Section E. You have to attempt only one of the choices in such questions
- (6) Use of calculators is not allowed.
- (7) You may use the following values of physical constants where ever necessary
  - (i)  $c = 3 \times 10^8$  m/s
  - (ii)  $m_e = 9.1 \times 10^{-31}$  kg
  - (iii)  $\mu_0 = 4\pi \times 10^{-7}$  TmA<sup>-1</sup>
  - (iv)  $\epsilon_0 = 8.854 \times 10^{-12} \times \text{C}^2\text{N}^{-1}\text{m}^{-2}$
  - (v) Avogadro's number =  $6.023 \times 10^{23}$  per gram mole

**SECTION - A**

- Q1. Which of the followings is the proper representation of a 10 cm long scale?  
(A) The scale of the length is 10 cm. (B) This is a 10 cm long scale.  
(C) This a 10 cm long scale. (D) The scale of the length is 10 cm.
- Q2. The displacement (in metres) of a body varies with time  $t$ (in second) as  
 $x = t^2 - 2t - 3$ .  
The displacement is zero for a positive value of  $t$  which is equal to  
(A) 1 s (B) 4 s (C) 3 s (D) 2 s
- Q3. If  $\vec{A} = \vec{B} + \vec{C}$  and the magnitudes of  $\vec{A}$ ,  $\vec{B}$  and  $\vec{C}$  are 5, 4 and 3, respectively, then the angle between  $\vec{A}$  and  $\vec{C}$  is  
(A)  $\sin^{-1} \left( \frac{3}{5} \right)$  (B)  $\cos^{-1} \left( \frac{3}{5} \right)$  (C)  $\cos^{-1} \left( \frac{4}{5} \right)$  (D)  $\sin^{-1} \left( \frac{4}{5} \right)$
- Q4. Application of lubricants cannot reduce  
(A) static friction (B) sliding friction (C) rolling friction (D) inertia
- Q5. A force of 49 N is just able to move a block of mass 10 kg on a rough horizontal surface.  
The coefficient of friction is  
(A) 0.5 (B) 1.0 (C) 0 (D) 0.8
- Q6. When a body is dropped from a tower, then there is an increase in its  
(A) weight (B) acceleration (C) velocity (D) gravitational potential energy
- Q7. A cyclist comes to a skidding stop in 20 m. During this process, the force on the cycle due to the road is 100 N and is directly opposed to the motion. Work done by the road on the cycle is  
(A) -2000 J (B) 2000 J (C) 1000 J (D) 100 J



- Q8. On which of the following factors moment of inertia of an object does not depend?  
 (A) Axis of rotation (B) Angular velocity  
 (C) Distribution of mass (D) Mass of an object
- Q9. Escape velocity of an object of mass  $m$  is proportional to  
 (A)  $m^2$  (B)  $m$  (C)  $m^{-1}$  (D)  $m^0$
- Q10. Rigidity modulus and Young's modulus are respectively  $\eta$  and  $Y$ . A copper wire of length  $L$  and area of cross-section  $A$  is so pulled that its length becomes  $5L$  and area of cross-section becomes  $\frac{A}{5}$ . So,  
 (A) its  $Y$  increases,  $\eta$  decreases. (B) Its  $\eta$  increases,  $Y$  decreases.  
 (C) its  $Y$  and  $\eta$  both increases. (D) Its  $Y$  and  $\eta$  both remain unchanged.
- Q11. When a system is taken from state 1 to state 3 along the path  $1 \rightarrow 2 \rightarrow 3$ , it is found that  $\Delta Q = 60 \text{ cal}$  and  $\Delta W = 10 \text{ cal}$ . Along the path  $1 \rightarrow 4 \rightarrow 3$ ,  $\Delta Q = 50 \text{ cal}$ ,  $\Delta W$  along the path  $1 \rightarrow 4 \rightarrow 3$  is



- (A) 10 cal (B) 40 cal (C) 0 cal (D) 60 cal
- Q12. A particle is executing simple harmonic motion. When its displacement is  $x$ , its total energy is  
 (A) Proportional to  $x$  (B) Proportional to  $\frac{1}{x}$   
 (C) Proportional to  $x^2$  (D) Independent of  $x$

Select the correct answer to these questions from the options is as given below.

- (A) If both Assertion and Reason are true and Reason is the correct explanation of Assertion.  
 (B) If both Assertion and Reason are true but Reason is not the correct explanation of Assertion.  
 (C) If Assertion is true but Reason is false.  
 (D) If both Assertion and Reason are false.
- Q13. **Assertion (A):**  $1 \text{ kg} = 10^9 \mu\text{g}$   
**Reason (R):**  $1 \text{ kg} = 10^3 \text{ g}$  and  $1 \text{ g} = 10^6 \mu\text{g}$ .
- Q14. **Assertion (A):** Direction of retardation is opposite to that of velocity.  
**Reason (R):** Retardation is equal to the rate of decrease of speed with time.
- Q15. **Assertion (A):** Mass and energy are not conserved separately. They are conserved as a single entity called mass-energy.  
**Reason (R):** Mass and energy are inter-convertible.
- Q16. **Assertion (A):** A person standing on a rotating platform suddenly stretches his arms, the platform slows down.  
**Reason (R):** A person by stretching his arms increases the moment of inertia and decreases angular velocity.

## **SECTION - B**

- Q17. What is rolling friction ?
- Q18. What is the differences between the following two data ?  
 (i) 85 km/h east, (ii) (8 h) (5 km/h east).

Q19. What is the turning effect of force called? On what factors does it depend?

Q20. Weight of a body should be greater in day or night. Why ?

Q21. What are fundamental note and overtones ?

**OR**

When a pendulum clock gains time, what adjustments should be made ?

### **SECTION - C**

Q22. Draw (a) acceleration – time (b) velocity – time (c) position – time graphs representing motion of an object under free fall. Neglect air resistance.

Q23. Define centripetal acceleration. Find the expression for it. Give one example of centripetal force.

Q24. What would happen if gravity suddenly disappeared?

Q25. State and prove Stefan-Boltzmann law.

Q26. Define root mean square velocity of gas molecules and give various relations for it.

Q27. State and prove Bernoulli's principle for the flow of non-viscous fluids and give its limitations.

Q28. The periodic time of a mass suspended by a spring (force constant  $k$ ) is  $T$ . If the spring is cut in three equal pieces, what will be the force constant of each part? If the same mass be suspended from one piece, what will be the periodic time?

**OR**

Given below are some examples of wave motion. State in each case, whether the wave motion is transverse, longitudinal or a combination both.

(i) Motion of a kink in a long coil spring produced by displacing one end of the string sideways.

(ii) Waves produced in a cylinder containing a liquid by moving its piston back and forth.

(iii) Waves produced by a motor boat sailing in water.

(iv) Light waves travelling from sun to earth.

(v) Ultrasonic waves in air produced by a vibrating quartz crystal.

### **SECTION - D**

Q29. Read the following paragraph and answer the questions that follow.

#### **Longitudinal and transverse wave:**

Longitudinal waves are defined as waves those are capable of displacing the medium in a direction either in the direction of the waves or opposite. Longitudinal mechanical waves are known as compressional waves. This is because these mechanical waves produce a lot of compression and rarefaction while travelling through medium. These waves are also called pressure waves as there is an increase and decrease in pressure while travelling. Sound waves like vibrations, P-Waves created through earthquakes, etc., are some kinds of longitudinal waves.

A transverse wave is defined as the wave that moves in the perpendicular direction of the vibration. One of the most important examples of transverse waves includes the waves created by the drum's beating. The membrane of the drum moves perpendicular to the surface. Another example of a transverse wave is light. Transverse wave travels through crests and troughs.

Transverse waves are mostly present in solids those have profound elasticity. In some cases, when there is a deformation in the material, the wave is called a shear wave.

(i) Which wave is also known as shear wave?

(A) Longitudinal wave

(B) Transverse wave

(C) Both (A) and (B)

(D) None of these



(ii) Which wave is also known as compressional wave?

- (A) Longitudinal wave (B) Transverse wave  
(C) Both (A) and (B) (D) None of these

(iii) Which wave is also known as pressure wave?

- (A) Longitudinal wave (B) Transverse wave  
(C) Both (A) and (B) (D) None of these

**OR**

Beating of drums produces

- (A) Longitudinal wave (B) Transverse wave  
(C) Both (A) and (B) (D) None of these

(iv) Which wave produces compressions and rarefactions in the medium?

- (A) Longitudinal wave (B) Transverse wave  
(C) Both (A) and (B) (D) None of these

Q30. Read the following paragraph and answer the questions that follow.

**Elasticity vs plasticity:**

Objects get deformed when pushed, pulled and twisted. Elasticity is the measure of the amount that the object can return to its original shape after these external forces and pressure are removed.

The opposite of elasticity is plasticity. When something is stretched, and it stays stretched, the material is said to be plastic. Such deformation is said to be plastic deformation.

In elastic deformation, atoms of the material are displaced temporarily from their original lattice site. They return back to their original position after the removal of external force. In plastic deformation, atoms of the solid are displaced permanently from their original lattice site. They don't return back to the original position even after the removal of external load. So, elastic deformation is temporary, whereas plastic deformation is permanent.

Amount of elastic deformation is very small. But the amount of plastic deformation is quite large.

External force required for elastic deformation of solid is quite small. Force required for plastic deformation is much higher. Total energy absorbed by the material during elastic and plastic deformation region is called **module of toughness**.

Energy absorbed by the material during elastic deformation is called **module of resilience**.

Most materials have an amount of force or pressure for which they deform elastically. If more force or pressure is applied, then they undergo plastic deformation. Materials those have a fair amount of plastic deformation before breaking are said to be ductile. Materials those can't stretch or bend much without breaking are said to be brittle. Copper, aluminium, etc. are ductile materials. For this reason those are used for making wires. Glass and ceramics are often brittle; they will not bend; they will break.

(i) Which of the following statements is false?

- (A) A body is said to be plastic when it deforms due to application of force and returns to its original shape when the deforming force is removed.  
(B) External force required for elastic deformation of solid is quite small.  
(C) In plastic deformation, atoms of the solid are displaced permanently from their original lattice site.  
(D) Most materials have an amount of force or pressure for which they deform elastically. If more force or pressure is applied, then they undergo plastic deformation.

(ii) Hooks law is applicable for

- (A) Plastic materials (B) Elastic materials (C) Both (A) and (B) (D) Brittle materials

(iii) Aluminium is a ..... material.

- (A) Brittle (B) Plastic (C) Ductile (D) Both (A) and (C)

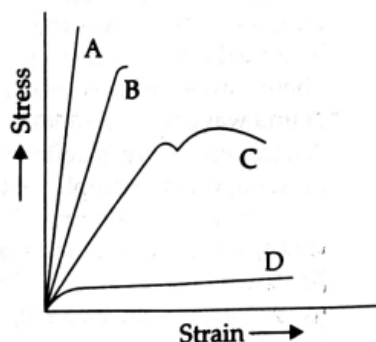
(iv) Ceramic is a ..... material.

- (A) Brittle (B) Plastic (C) Ductile (D) Both (A) and (C)

**OR**



Which of the following 4 stress–strain graphs represent a ductile material and a brittle material?



- (A) A is for a brittle material, B is for a ductile material  
 (B) A is for a brittle material, D is for a ductile material  
 (C) A is for a brittle material, C is for a ductile material  
 (D) C is for a brittle material, A is for a ductile material

### SECTION - E

Q31. What are the various types of equilibrium?

**OR**

Explain the concept of angular momentum. Also derive an expression for angular momentum in cartesian co-ordinate.

Q32. Write the S. I. units of the following physical quantities—

- (a) Luminous intensity,
- (b) Temperature,
- (c) Plane angle,
- (d) Electric current,
- (e) Amount of substance,
- (f) Solid angle,
- (g) Pressure.

**OR**

What are the important points about the uniform motion?

Q33. There are 3 liquids A, B and C of same mass. Their temperatures are  $14^{\circ}\text{C}$ ,  $24^{\circ}\text{C}$  and  $40^{\circ}\text{C}$  respectively. When A and B are mixed, the final temperature of the mixture becomes  $20^{\circ}\text{C}$ . When B and C are mixed, the final temperature of the mixture becomes  $34^{\circ}\text{C}$ . What will be the final temperature of the mixture when all the three liquids are mixed together?

**OR**

Derive an expression for work done in isothermal process.



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**SOLUTION**

Q1. (A)

**Explanation:** While units are symbolically represented, there should not be any dots. But if it appears at the end of a sentence, then a dot may appear as a full-stop..

Q2. (C)

**Explanation:**  $x = t^2 - 2t - 3$

For  $x = 0$

$$0 = t^2 - 2t - 3 \text{ Or,}$$

$$0 = (t + 1)(t - 3)$$

$$\therefore t = 3, -1$$

Positive value of  $t$  is 3 s.

Q3. (B)

**Explanation:**  $\vec{A} = \vec{B} + \vec{C}$

$$\text{Or, } \vec{A} - \vec{C} = \vec{B}$$

$$\text{Or, } (\vec{A} - \vec{C})^2 = (\vec{B})^2$$

$$\text{Or, } A^2 + C^2 - 2\vec{A} \cdot \vec{C} = B^2$$

$$\text{Or, } 25 + 9 - 2AC \cos \theta = 16$$

$$\text{Or, } 34 - 2 \times 5 \times 3 \cos \theta = 16$$

$$\text{Or, } 30 \cos \theta = 18$$

$$\text{Or, } \cos \theta = \frac{18}{30} = \frac{3}{5}$$

$$\therefore \theta = \cos^{-1} \left( \frac{3}{5} \right)$$

Q4. (D)

Q5. (A)

**Explanation:** The box is just able to move when

$$F = f_s$$

( $F$  = force applied,  $f_s$  = force of static friction)

Since

$$f_s = \mu N$$

$$F = \mu N$$

$$\text{Or, } \mu = \frac{F}{N}$$

$$\text{Or, } \mu = \frac{49}{mg}$$

$$\text{Or, } \mu = \frac{49}{(10 \times 9.8)}$$

$$\therefore \mu = 0.5$$

Q6. (C)

**Explanation:** When a body is dropped it is subjected to a constant acceleration. Hence, its velocity increases.

Q7. (A)

**Explanation:**

$$W = F \cos 180^\circ = 100 \times 20 \times (-1) = -2000 \text{ J}$$

Q8. (B)



Q9. (D)

**Explanation:** Escape velocity =  $\sqrt{2gR}$

It is independent of mass.

Q10. (D)

**Explanation:** Modulus of elasticity does not change with dimension. It depends on material only.

Q11. (A)

**Explanation:** From 1st law of thermodynamics,

$$\Delta Q = \Delta U + \Delta W$$

Along 1  $\rightarrow$  2  $\rightarrow$  3 path,

$$60 = \Delta U + 10$$

$$\therefore \Delta U = 40 \text{ cal}$$

Along 1  $\rightarrow$  4  $\rightarrow$  3 path,

$$50 = 40 + \Delta W$$

$$\therefore \Delta W = 10 \text{ cal}$$

Q12. (D)

**Explanation:**

$$\text{Total energy} = \frac{1}{2} m \omega^2 A^2$$

So, it is independent of  $x$ .

Q13. (A)

**Explanation:** 1 kg =  $10^3$  g

Or, 1 kg =  $10^3 \times 10^6 \mu\text{g}$

$$\therefore 1 \text{ kg} = 10^9 \mu\text{g}$$

So, assertion and reason both are true. Reason explains the assertion.

Q14. (B)

**Explanation:** Retardation is applied to the opposite direction of the velocity to reduce the velocity.

So, the assertion is true.

$$\text{Retardation} = \frac{\text{Decrease in velocity}}{\text{Time difference}}$$

Hence, the reason is also true but it does not explain the assertion

Q15. (A)

**Explanation:** According to Einstein's theory, mass and energy are related as

$$E = mc^2$$

where,

$E$  = Energy

$m$  = mass

$c$  = speed of light

So, mass and energy are not conserved separately. They are conserved as a single entity.

Hence, assertion and reason both are true and the reason explains the assertion.

Q16. (A)

**Explanation:** From law of conservation of angular momentum,

$$I_1 \omega_1 = I_2 \omega_2$$

When the person stretches his arms, his moment of inertia increases i.e.,  $I_2 > I_1$

So,  $\omega_2 < \omega_1$

So, the assertion and reason both are true and the reason explains the assertion.

Q17. The opposition offered to the circular motion of objects like ring, disc, sphere, cylinder, etc. on another surface is called rolling friction. The coefficient of rolling friction ( $\mu_r$ ) is smaller than the coefficient of kinetic friction ( $\mu_k$ ). The sliding friction can be decreased a lot by converting it into rolling friction.

Q18. (i) It is the product of a pure number and a vector (velocity). Hence, the unit of product is the same as that of vector, i.e., the product is a velocity of 85 km/h, towards east.



(ii) It is the product of a scalar (time) and a vector (velocity). Hence, the unit of the product will be  $\text{h} \times (\text{km/h}) = \text{km}$ . Thus, the product is a displacement of magnitude 40 km, towards east.

Q19. Turning effect of force is called torque. Factors on which it depends are

- (i) Magnitude of force,
- (ii) Perpendicular distance of force vector from axis of rotation.

Q20. It should be greater in night. In the day time the body is pulled by Earth and Sun in two opposite directions. This will result into decrease in weight.

During night time the Earth and the Sun pull the body in the same direction so the weight will increase in night.

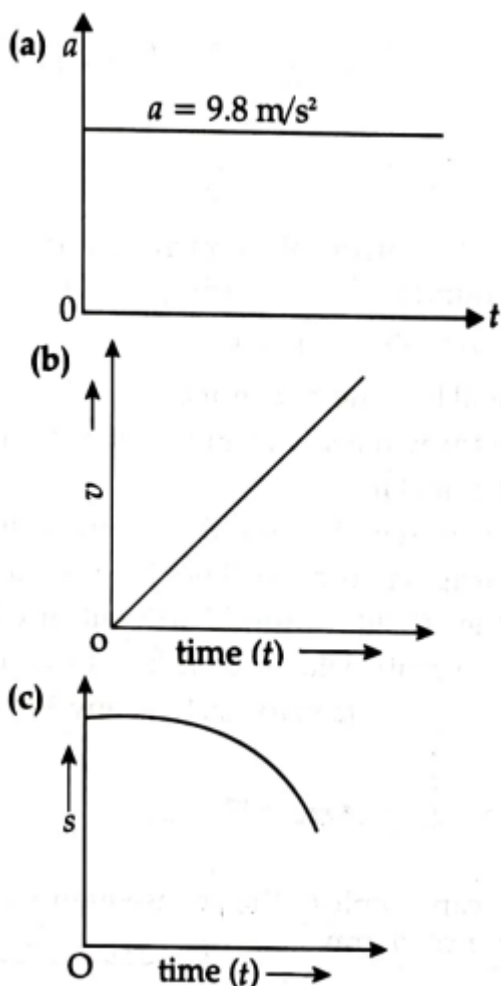
Q21. When a source is sounded, it generally vibrates in more than one mode and therefore, emits tones of different frequencies. Then tone of lowest frequency is called the fundamental note and the tone of higher frequencies is called overtones

OR

When a pendulum clock gains time, it means it has gone fast, i.e., it makes more vibrations per day than required.

This shows that the time period of oscillation has decreased. Therefore, to correct it, the length of pendulum should be properly increased.

Q22.

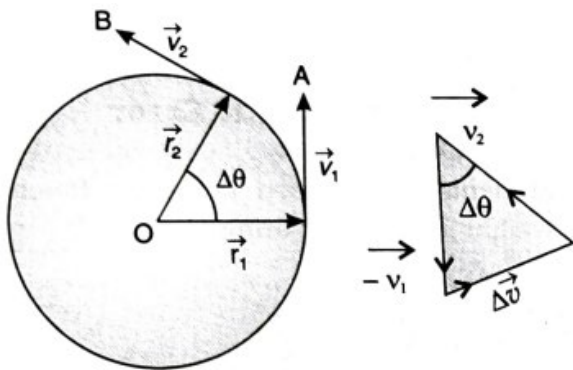


Q23. Acceleration acting on the object undergoing uniform circular motion is called centripetal acceleration.

**Expression :** Consider a particle of mass  $m$ , moving with a constant speed  $v$  and uniform angular velocity  $\omega$ , on a circular path of radius  $r$  with centre at  $O$ .







Angular speed  $\omega = \frac{\Delta\theta}{\Delta t} \dots (1)$

Let  $\vec{v}_1$  and  $\vec{v}_2$  be the velocity vectors. Then  
Then

$$\Delta\theta = \omega\Delta t = \frac{|\Delta\vec{v}|}{|\vec{v}|}$$

Here  $|\vec{v}_1| = |\vec{v}_2| = |\vec{v}|$

or

$$\frac{|\Delta\vec{v}|}{\Delta t} = |\vec{v}| \omega = (\omega r)\omega = \omega^2 r$$

When  $\Delta t \rightarrow 0$  then  $\frac{|\Delta\vec{v}|}{\Delta t}$  represents the magnitude of centripetal acceleration, which is given by

$$|\vec{a}| = \frac{|\Delta\vec{v}|}{\Delta t} = \omega^2 r = \left(\frac{v}{r}\right)^2 r = \frac{v^2}{r} \text{ then, } |\vec{a}| = \omega^2 r = \frac{v^2}{r}$$

**Example of centripetal acceleration** is a stone moved around tied to the string.

Q24. If gravity suddenly disappears,

- (i) All bodies will lose their weights.
- (ii) We shall be thrown away from the surface of Earth due to centrifugal force.
- (iii) The motion of planets around the Sun will cease because centripetal force shall not be provided.
- (iv) Motion of the satellite around Earth will also be not possible as no centripetal force will be provided.

Q25. It states that the power ( $E$ ) emitted per unit area by a body at absolute temperature  $T$ , is given by

$$E = \varepsilon\sigma T^4$$

where,

$E$  = Energy being emitted per second per unit area of surface

$\varepsilon$  = Emissivity or emissive power of that body

(which is equal to 1 for black body)

$\sigma$  = Stefan's constant

$$= 5.67 \times 10^{-8} \text{ J m}^{-2} \text{ K}^{-4} \text{ s}^{-1}$$

If temperature of the surrounding is to be taken into consideration then the net rate of loss of energy as heat per unit area per second is given by  $E = \varepsilon\sigma(T^4 - T_0^4)$

If the total area or surface is  $A$ , then the total energy radiated in time  $E = A\varepsilon\sigma(T^4 - T_0^4)$

Q26. Root mean square velocity is defined as the square root of the average of the squares of the individual velocities of the gas molecules, i.e.,

$$v_{rms} = \sqrt{\frac{v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2}{n}} = \sqrt{\overline{v^2}}$$

where,  $v_1, v_2, v_3, \dots, v_n$  are individual velocities

$$v_{rms} = \sqrt{\frac{3P}{\rho}} = \sqrt{\frac{3RT}{M}} = \sqrt{\frac{3k_B T}{m}}$$

$$\text{i.e., } v_{rms} \propto \sqrt{T}$$



Q27. **Statement:** Bernoulli's theorem: Bernoulli's theorem state that the total energy per unit volume (pressure energy, P.E. and K.E.) per unit volume of an incompressible non-viscous liquid in steady flow remain constant throughout the flow of the liquid

$$P + \rho gh + \frac{1}{2}\rho v^2 = \text{constant.}$$

**roof:** Consider an incompressible non-viscous liquid entering at A at height  $h_1$  having cross-section  $A_1$  with a velocity  $v_1$  and coming out at B at a height  $h_2$  having area of cross-section  $A_2$  with velocity  $v_2$ .

The P.E. and K.E. increase since  $h_2$  and  $v_2$  are more than  $h_1$  and  $v_1$ , respectively. Let  $P_1$  and  $P_2$  are the pressures at A and B.

The work done per second on the liquid at A =  $-P_1 A_1 v_1$

The work done per second by the liquid at B =  $-P_2 A_2 v_2$

and  $A_1 v_1 = A_2 v_2$  are the volumes of liquid entering at A and leaving at B per second, respectively. These volumes must be equal and so  $A_1 v_1 = A_2 v_2 = \frac{m}{\rho}$

Net work done on the liquid =  $(P_1 - P_2) \frac{m}{\rho}$

where  $m$  = mass of liquid entering at A or leaving from B in 1 second.

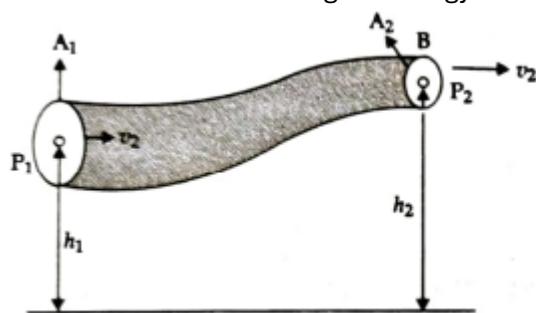
Kinetic energy of the liquid at A is  $\frac{1}{2} m v_1^2$

Kinetic energy of the liquid at B is  $\frac{1}{2} m v_2^2$

So, change in kinetic energy =  $\frac{1}{2} m (v_2^2 - v_1^2)$

Change in potential energy =  $m g (h_2 - h_1)$

Net work done = Net change in energy



$$(P_1 - P_2) = \rho g (h_2 - h_1) + \frac{\rho}{2} (v_2^2 - v_1^2)$$

$$\text{i.e., } P_1 + \rho g h_1 + \frac{\rho}{2} v_1^2 = P_2 + \rho g h_2 + \frac{\rho}{2} v_2^2$$

$$\text{i.e., } \frac{P}{\rho g} + h + \frac{v^2}{2g} = \text{constant}$$

**Bernoulli's Theorem Limitations :**

1. While deriving Bernoulli's theorem it is assumed that velocity of every particle of liquid across any cross section of tube is uniform. Practically it is incorrect.
2. The viscous drag of the liquid which comes into play when liquid is in motion has not been taken into account.
3. While deriving the equation, it is assumed that there is no loss of energy when liquid is in motion.

Q28. Consider the spring be made of combination of three springs in series each of spring constant  $k$ .

The effective spring constant  $K$  is given by:

$$\frac{1}{K} = \frac{1}{k} + \frac{1}{k} + \frac{1}{k} = \frac{3}{k}$$

$$\text{or } K = \frac{k}{3}$$



Or  $k = 3K$

∴ Time period of vibration of a body attached to the end of this spring,

$$\begin{aligned} T &= 2\pi \sqrt{\frac{m}{K}} \\ &= 2\pi \sqrt{\frac{m}{(k/3)}} \\ &= 2\pi \sqrt{\frac{3m}{k}} \dots (i) \end{aligned}$$

When the spring is cut into three pieces, each having spring constant  $= k$ .

Time period of vibration of a body attached to the end of this spring,

$$T_1 = 2\pi \sqrt{\frac{m}{k}} \dots (ii)$$

From the Eq. (i) and (ii),

$$\begin{aligned} \frac{T_1}{T} &= \frac{1}{\sqrt{3}} \\ \therefore T_1 &= \frac{T}{\sqrt{3}} \end{aligned}$$

OR

(i) When the spring is pulled sideways, the kink moves at  $90^\circ$  to the length of the spring. Waves are transverse.

(ii) Waves in this case are longitudinal, because molecules of the liquid will move along the direction of motion of the piston.

(iii) The water surface is cut laterally and pushed backwards by the propeller of motor boat. Therefore, the waves are the mixture of longitudinal and transverse waves.

(iv) Light waves (from sun to earth) are electromagnetic waves which are transverse in nature.

(v) Ultrasonic waves in air are basically sound waves of frequency greater than the audible frequencies. They are, therefore, longitudinal waves.

Q29. (i) (B).

**Explanation:** Transverse waves are mostly present in solids those have profound elasticity. In some cases, when there is a deformation in the material, the wave is called a shear wave.

(ii) (A)

**Explanation:** Longitudinal mechanical waves are known as compressional waves. This is because these mechanical waves produce a lot of compression and rarefaction while travelling through medium.

(iii) (A)

**Explanation:** These waves are also called as pressure waves as there is an increase and decrease in pressure while travelling.

OR

(B)

**Explanation:** One of the most important examples of transverse waves includes the waves created by the drum's beating. The membrane of the drum moves perpendicular to the surface.

(iv) A

**Explanation:** Longitudinal mechanical waves produce a lot of compression and rarefaction while travelling through medium. Hence, they are also known as compressional waves.

Q30. (i) (A)

**Explanation:** A body is said to be elastic when it deforms due to application of force and returns to its original shape when the deforming force is removed. The opposite of elasticity is plasticity.

When something is stretched, and it stays stretched, the material is said to be plastic.



(ii) (B)

**Explanation:** Hooks law is applicable only for elastic materials which states that, for relatively small deformation of an object, the displacement or size of the deformation is directly proportional to the deforming force. Under these conditions, the object returns to its original shape and size upon removal of the load.

(iii) (C)

**Explanation:** Aluminium is a ductile material. It can undergo substantial plastic deformation prior to fracture.

(iv) (A)

**Explanation:** Ceramic when subjected to little stress, it fractures with little elastic deformation and without significant plastic deformation. Hence, it is a brittle material.

OR

(C)

**Explanation:** A typical stress-strain curve for a brittle material is linear. Hence, graph A is for brittle material. Graph C is for a ductile material.

Q31. Different types of equilibrium are—

**Stable :**

(i) When a particle is displaced slightly from a position, then a force acting on it brings it back to the initial position. It is said to be in stable equilibrium position.

(ii) Potential energy is minimum.

(iii)  $\frac{d^2U}{dx^2} = \text{positive}$

(iv) **Example:** A marble placed at the bottom of a hemispherical bowl.

**Unstable :**

(i) When a particle is displaced slightly from a position, then a force acting on it tries to displace the particle further away from the equilibrium position, it is said to be in unstable equilibrium position.

(ii) Potential energy is maximum

(iii)  $\frac{d^2U}{dx^2} = \text{negative}$

(iv) **Example:** A marble balanced on top of a hemispherical bowl.

**Neutral :**

(i) When a particle is slightly displayed from a position it does not experience any force acting on it and continues to be in equilibrium in the displaced position, it is said be in neutral equilibrium.

(ii) Potential is constant

(iii)  $\frac{d^2U}{dx^2} = 0$

(iv) **Example:** A marble placed on a horizontal table.

OR

**The concept of angular momentum :**

(i) The angular momentum of a particle with respect to a point gives an idea of the strength of its rotational tendency about that point.

(ii) The magnitude of the angular momentum is defined in terms of mass and velocity of the particle and its distance from the reference point, i.e.,

$$L = mvr.$$

(iii) The vector concept of the angular momentum is useful. Its direction is the axial direction given by right hand rule. The direction of  $\vec{L}$  is  $\perp$  to the plane containing  $\vec{r}$  and  $\vec{v}$

**Expression for angular momentum in cartesian co-ordinates :**

Let us consider a particle of mass  $m$  rotating in  $x - y$  plane.

$P$  be its position at any instant. Its position vector is  $\vec{r}$ .

$$\overrightarrow{OP} = \vec{r}$$

$$\angle XOP = \theta$$

In time  $dt$  the particle reaches  $Q$  under the action of force



$$\vec{F} = \vec{P}_A$$

$$\vec{OQ} = \vec{r} + d\vec{r}$$

$$\angle POQ = d\theta$$

Now

$$\vec{OP} + \vec{PQ} = \vec{OQ}$$

$$\text{Or, } \vec{PQ} = \vec{OQ} - \vec{OP}$$

$$\text{Or, } \vec{PQ} = \vec{r} + d\vec{r} - \vec{r}$$

$\therefore$

$$\vec{PQ} = d\vec{r}$$

Work done to rotate the particle from  $P$  to  $Q$  is  $dW$

$$dW = \vec{F} \cdot d\vec{r}$$

$$\text{or, } dW = (F_x \hat{i} + F_y \hat{j})(dx \hat{i} + dy \hat{j})$$

$$\text{or, } dW = F_x dx + F_y dy$$

$$\text{or, } dW = F_x(-y d\theta) + F_y(x d\theta)$$

$$\text{or, } dW = x F_y d\theta - y F_x d\theta$$

$$\text{or, } dW = (x F_y - y F_x) d\theta$$

$$\therefore dW = \tau d\theta$$

Where  $\tau = (x F_y - y F_x) \dots (1)$

$$\tau = F_x dy - F_y dx \dots (i)$$

According to Newton's 2nd law of motion

$$F_x = \frac{dp_x}{dt} = \frac{d}{dt}(mv_x)$$

$$= m \frac{dv_x}{dt}$$

$$F_y = \frac{dp_y}{dt} = \frac{d}{dt}(mv_y)$$

$$= m \frac{dv_y}{dt}$$

Substituting in (1), we get

$$\tau = xm \frac{dv_y}{dt} - ym \frac{dv_x}{dt}$$

or

$$\tau = m \left[ x \frac{dv_y}{dt} - y \frac{dv_x}{dt} \right] \dots (2)$$

Now, differentiating  $(xv_y - yv_x)$ ,

$$\frac{d}{dt}(xv_y - yv_x) = x \frac{dv_y}{dt} + v_y \frac{dx}{dt} - y \frac{dv_x}{dt} - v_x \frac{dy}{dt}$$

$$= x \frac{dv_y}{dt} + v_y v_x - y \frac{dv_x}{dt} - v_x v_y$$

$$\left[ \because \frac{dx}{dt} = v_x, \frac{dy}{dt} = v_y \right]$$

$$= x \frac{dv_y}{dt} - y \frac{dv_x}{dt} \dots (3)$$

Substituting (3) in (2), we get

$$\tau = m \frac{d}{dt}(xv_y - yv_x)$$

$$\tau = \frac{d}{dt}(xmv_y - ymv_x)$$

As

$$\tau = \frac{d}{dt}(xp_y - yp_x) \dots (4)$$



$$xp_y - yp_x = L$$

or  $\tau = \frac{dL}{dt}$

- Q32. (a) candela (cd)  
 (b) kelvin (K)  
 (c) radian (rad)  
 (d) ampere (A)  
 (e) mole (mol)  
 (f) steradian (Sr)  
 (g)  $\text{N/m}^2 = \text{pascal (pa)}$

**OR**

Following are some important points about the uniform motion :

- (i) The velocity in uniform motion does not depend upon the time interval  $(t_2 - t_1)$ .
- (ii) The velocity in uniform motion is independent of the choice of origin.
- (iii) No force acts on the object having uniform motion.
- (iv) Velocity is taken to be positive when the object moves towards right of the origin and it is taken negative if the object moves towards left of the origin.

- Q33. Mass of each liquid =  $m$

Specific heat of liquids  $A, B$  and  $C$  are respectively  $s_A, s_B$  and  $s_C$ .

When  $A$  and  $B$  are mixed:

Heat gained by  $A$  = Heat lost by  $B$

Or,

$$m \times s_A \times (20 - 14) = m \times s_B \times (24 - 20)$$

$$\therefore \frac{s_A}{s_B} = \frac{2}{3}$$

When  $B$  and  $C$  are mixed:

Heat gained by  $B$  = Heat lost by  $C$

Or,

$$m \times s_B \times (34 - 24) = m \times s_C \times (40 - 34)$$

$$\therefore \frac{s_C}{s_B} = \frac{5}{3}$$

When three liquids are mixed together:

Since there is no heat supplied externally,

Heat gained by  $A$  + Heat gained by  $B$  + Heat gained by  $C$  = 0

Let the final temperature be  $t^\circ\text{C}$ .

$$m \times s_A \times (t - 14) + m \times s_B \times (t - 24) + m \times s_C \times (t - 40) = 0$$

Or,

$$s_A \times (t - 14) + s_B \times (t - 24) + s_C \times (t - 40) = 0$$

Or,

$$\left(\frac{s_A}{s_B}\right) \times (t - 14) + (t - 24) + \left(\frac{s_C}{s_B}\right) \times (t - 40) = 0$$

Or,

$$\left(\frac{2}{3}\right) \times (t - 14) + (t - 24) + \left(\frac{5}{3}\right) \times (t - 40) = 0$$

Or,

$$2t - 28 + 3t - 72 + 5t - 200 = 0$$

$$\therefore t = 30^\circ\text{C}$$

**OR**



Suppose 1 g mole of an ideal gas enclosed in a cylinder of conducting walls. Let  $P_1, V_1, T$  be initial pressure, volume and temperature. Let gas expand to volume  $V_2$  where pressure reduces to  $P_2$  and temperature remains constant.

If  $A$  is the area of piston

$$F = P \times A$$

$$dW = F \times dx$$

$$W = \int_{V_1}^{V_2} P dV [\because A dx = dV]$$

But,

$$PV = RT$$

$$W = \int_{V_1}^{V_2} \frac{RT}{V} dV$$

$$W = RT [\log_e V]_{V_1}^{V_2}$$

$$W = RT (\log_e V_2 - \log_e V_1)$$

$$W = 2.303 RT \log_{10} \left( \frac{V_2}{V_1} \right)$$

